

Galerkin projection and Weak Formulation

Weak formulation:

$$Au = v \longrightarrow \langle Au, f \rangle = \langle v, f \rangle$$

- Differential equations
- Integral equations

$$\alpha(u, f)$$

→ Here: solution has to hold for all increments

→ (Babuska) Lax-Milgram theorem establishes existence and uniqueness of weak formulation

Thm (Lax-Milgram):

Let $(H, \langle \cdot, \cdot \rangle)$ be a Hilbert space and $a(\cdot, \cdot)$ a bilinear form on H with $0 < \gamma \leq T < \infty$ satisfying:

- $a(v, v) \geq \gamma \|v\|^2$ (H-ellipticity)
- $a(u, v) \leq T \|u\| \|v\|$ (boundedness)

Then

$$a(u, v) = f(v) \quad \forall f \in H'$$

has a unique solution $u \in H$.

Q

The weak form for an integral equation:

$$\int_X k(x, y) u(x) dx = v(y)$$

is

$$\iint_{X \times X} k(x, y) u(x) f(y) dx dy = \int_Y v(y) f(y) dy$$

- H-ellipticity: $k(x, y)$ does not have a nullspace
- boundedness: $k(x, y)$ yields finite result

Ex

The Heaviside step function is defined as

$$H(x) = \begin{cases} 1 & x \geq 0 \\ 0 & x < 0 \end{cases}$$

We have

$$\int_{-\infty}^{\infty} H(x) f'(x) dx = \underbrace{\left[f(x) H(x) \right]_{-\infty}^{\infty}}_{\substack{\text{Assume } f(x) \text{ is smooth} \\ \text{and has compact support} \\ \Rightarrow = 0}} - \int_{-\infty}^{\infty} f(x) H'(x) dx$$

$$= \int_0^{\infty} f'(x) dx$$

$$= \left[f(x) \right]_0^{\infty}$$

$$= f(\infty) - f(0)$$

$$= -f(0)$$

$$\Rightarrow \int_{-\infty}^{\infty} f(x) H'(x) dx = f(0)$$

$$\Rightarrow H'(x) = \delta_0(x)$$

in a weak sense

→ Generalizing and systematizing this idea yields to Laurent Schwartz's theory of distributions (which was first developed by E. Borel)

The bilinear form $a(\cdot, \cdot)$ satisfies

$$a(u_n, v_n) = f(v_n)$$

where $u_n, v_n \in H_n \subset H$ is a finite sub-space.

↳ Using basis representation yields a matrix vector equation for the above weak formulation.

- How good is the approximation?
- How large has n to be to attain a prescribed error?
- Which basis should one use?

The discrete and continuous solutions satisfy

$$a(u_n, v_n) = f(v_n) \quad \forall v_n \in H_n$$

$$a(u, v) = f(v) \quad \forall v \in H$$

Since $H_n \subset H$ this implies

$$a(u, v_n) = f(v_n) \quad \forall v_n \in H_n$$

Subtracting this from the discrete weak form we obtain

$$a(u, v_n) - a(u_n, v_n) = f(v_n) - f(v_n)$$

and using the bilinearity of $a(\cdot, \cdot)$ we have

$$a(u - u_n, v_n) = 0.$$

→ $a(\cdot, \cdot)$ satisfies

$$a(0, v) = 0 \quad \forall v \in H$$

$$a(u, v) = T \|u\| \|v\|$$

Hence, if $a(\cdot, \cdot)$ is symmetric it defines an inner product

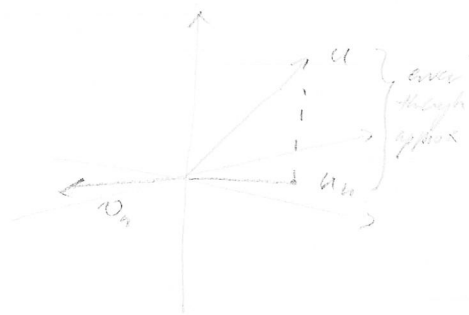
The equation

$$a(u - u_n, v_n) = 0$$

is thus a generalization of

$$\langle u - u_n, v_n \rangle = 0$$

→ To gain some intuition let $H = \mathbb{R}^2$ and $H_n = \mathbb{R}^1$



the largest vector u_n that satisfies the above equation is the orthogonal projection of u

→ An example for a non-trivial inner product is

$$\langle u, v \rangle_A = u^T A v = u^T \begin{pmatrix} a_{11} & 0 \\ 0 & a_{22} \\ & & a_{33} \end{pmatrix} v, \quad a_{ii} > 0$$

↳ As we will see later, this example is in some sense generic, i.e. all symmetric $a(\cdot, \cdot)$ have this form

→ Can we make the observation that the optimal u_n is the $a(\cdot, \cdot)$ -orthogonal projection onto H_n .

By H -ellipticity we have:

$$\begin{aligned} \|u - u_n\|^2 &\leq \frac{1}{\gamma} a(u - u_n, u - u_n) \\ &= \frac{1}{\gamma} a(u - u_n, u - v_n + v_n - u_n) \end{aligned}$$

$$= \frac{1}{\gamma} \left(a(u - u_n, u - v_n) \right.$$

$$+ a(u - u_n, v_n) \left. \right)$$

$$+ a(u - u_n, -u_n) \left. \right)$$

$\left. \begin{array}{l} \gamma = 0 \\ \text{by} \\ \text{a.b.} \\ \text{orthogonality} \end{array} \right\}$

$$= \frac{1}{\gamma} a(u - u_n, u - v_n)$$

$$\leq \frac{1}{\gamma} \|u - u_n\| \|u - v_n\|$$

Since v_n is arbitrary the optimal bound is

$$\|u - u_n\| \leq \frac{1}{\gamma} \min_{v_n \in H_n} \|u - v_n\|$$

The v_n that minimizes

this is the $a(\cdot, \cdot)$ -orthogonal projection of u onto H_n .

→ The above result is known as Leja's Lemma

→ Closely related to the error is the convergence rate that measures how fast the error decays as n increases.

↳ Depends on the choice of basis